12. . System will be in static equilibrium for all positions of the bead if there is no change in P.E. when moved from one position to another.

Let H be the highest point of the curve and consider when bead is at B Taking a horizontal plane through the ring as . zero level for P.E. we have

P.E. of system when bead is at *H* is mgh - mg(x - h) where *x* is Taking horizontal plane through O as zero level for P.E. we have

P.E. of system when bead is at *H* is mgh - mg(x - h) where *x* is the length of the string.

P.E. when bead is at *B* is $mgr \cos \theta - mg(x - r)$ so there is no change in P.E if $mgh - mg(x - h) = mgr \cos \theta - mg(x - r)$ $\Rightarrow h + h = r \cos \theta_{-} + r$ or $r = \frac{2h}{1 + \cos \theta}$ which is the equation of the curve. shortest distance of curve from ring is obviously when $1 + \cos \theta$ is a maximum, i.e. $\cos \theta = 1$ so minimum value of *r* is *h*, i.e. h = d and equation is $r(1 + \cos \theta) = 2d$

$$\cos\theta = \frac{2d}{r} - 1 \Rightarrow -\sin\theta\dot{\theta} = -\frac{2d}{r^2}\dot{r} \text{ and } \sin\theta = \sqrt{1 - \left(\frac{2d}{r} - 1\right)^2} = \frac{\sqrt{4dr - 4d^2}}{r}$$
$$\operatorname{so} \dot{\theta} = \frac{2d}{r^2} \times \frac{r\dot{r}}{\sqrt{4dr - 4d^2}} = \frac{d\dot{r}}{r\sqrt{dr - d^2}} \Rightarrow \dot{\theta}^2 = \frac{d^2\dot{r}^2}{r^2(dr - d^2)} = \frac{d\dot{r}^2}{r^2(r - d)}$$

P.E. constant \Rightarrow K.E. constant speed of *P* is \dot{r}

at *B*, bead has a speed of $r\dot{\theta}$ tangentially and $-\dot{r}$ radially so by the constancy of K.E. $(r\dot{\theta})^2 + 2\dot{r}^2 = v^2 \Rightarrow \left(\frac{r^2d}{r^2(r-d)} + 2\right)\dot{r}^2 = v^2 \Rightarrow \left(\frac{2r-d}{r-d}\right)\dot{r}^2 = v^2 \Rightarrow \dot{r}^2 = \left(\frac{r-d}{2r-d}\right)v^2$ so $\dot{\theta}^2 = \frac{d}{r^2(r-d)} \times \left(\frac{r-d}{2r-d}\right)v^2 = \left(\frac{d}{r^2(2r-d)}\right)v^2$ and $(r\dot{\theta})^2 = \left(\frac{d}{2r-d}\right)v^2$

so finally the speed of the bead is $\left(\left(r\dot{\theta}\right)^2 + \dot{r}^2\right)^{\frac{1}{2}} = \left(\left(\frac{d}{2r-d}\right) + \left(\frac{r-d}{2r-d}\right)\right)^{\frac{1}{2}}v = \left(\frac{r}{2r-d}\right)^{\frac{1}{2}}v$ as required

